



PRACTICAL CHECK SHEET

| Candidate: | | | | Successful | |
|-------------------------|---|--|--------------|--------------------|--|
| Evaluator: | | | Unsuccessful | | |
| Date: | | | 1006 | -PROCESS-19 | |
| | | | | | |
| Standard: | | NFPA 1006 – 2021 edition – 5.2.14 | | | |
| Task: | | Direct a lowering operation in a high-angle environment | | | |
| Performance Outcome: | | The movement is controlled, the load can be held in place when needed, operating methods do not stress the system to the point of failure, rope commands are used to direct the operation, and potential problems are identified, communicated, and managed. | | | |
| Conditions: | | Given rescue personnel, an established lowering system, a specified minimum travel distance for the load, and a load to be moved | | | |
| Candidate Directive: | | "Using the provided lowering system and personnel, direct the lowering operation to move the load the indicated distance." | | | |
| | | TABLE STEPS TEST | | | |
| | | | TF | ST | |
| NO. | | TASK STEPS | Successful | ST Unsuccessful | |
| NO. | The mov | TASK STEPS rement was controlled | | 1 | |
| | | | | 1 | |
| 1 | The load | rement was controlled | | 1 | |
| 1 2 | The load Operatin the point | rement was controlled I could be held in place when needed g methods did not stress the system to of failure mmands were used to direct the | | 1 | |
| 1 2 3 | The load Operatin the point Rope co- operation Potential | rement was controlled I could be held in place when needed g methods did not stress the system to of failure mmands were used to direct the | | 1 | |
| 1 2 3 4 5 | The load Operatin the point Rope co- operation Potential commun | rement was controlled I could be held in place when needed g methods did not stress the system to of failure mmands were used to direct the n I problems were identified, | | 1 | |
| 1 2 3 4 5 | The load Operatin the point Rope co- operation Potential commun | rement was controlled I could be held in place when needed ag methods did not stress the system to a of failure mmands were used to direct the and problems were identified, icated, and managed | | 1 | |
| 1 2 3 4 5 | The load Operatin the point Rope co- operation Potential commun | rement was controlled I could be held in place when needed ag methods did not stress the system to a of failure mmands were used to direct the and problems were identified, icated, and managed | | 1 | |

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