



Candidate:			Successful	
Evaluator:		 Ur	nsuccessful 🗌	
Date:			1006	-PROCESS-06
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.1		
Task	(:	Perform size up of a rescue incident		
Performance Outcome:		The type of rescue is determined, the nur the last reported location of all victims is a reporting parties are identified and intervi assessed, search parameters are identified develop an incident action plan is obtained	established, witr ewed, resource ed, and informat	nesses and needs are
Cond	ditions:	Given background information and applic	able reference r	naterials
Candidate Directive:		"Using the simulated incident scene and size up of the scene."	witnesses you s	ee, perform a
NO		TAOK OTEDO	TE	ST
NO.		TASK STEPS	Successful	Unsuccessful
1	The type	of rescue was determined		
2	The num	ber of victims was identified		
3	The last reported location of all victims was			
	establish	·		
4		ned es and reporting parties were identified		
4 5	Witnesse and inter	ned es and reporting parties were identified		
	Witnesse and inter Resource	ned es and reporting parties were identified viewed		
5	Witnesse and inter Resource Search p	ned es and reporting parties were identified eviewed e needs were assessed		
5 6 7	Witnesse and inter Resource Search p Informati plan was	ned es and reporting parties were identified eviewed e needs were assessed parameters were identified ion required to develop an incident action		
5 6 7	Witnesse and inter Resource Search p Informati plan was	es and reporting parties were identified viewed e needs were assessed parameters were identified ion required to develop an incident action is obtained.		





Candidate:				Successful	
Evaluator:			Uı	nsuccessful	
Date:		1006	-PROCESS-07		
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.2			
Task	/ a \	Maintain hazard-specific PPE			
	ormance come:	Damage, defects, and wear are identified equipment functions as designed, and probeen performed and documented consist recommendations.	eventive mainte	nance has	
Conditions:		Given clothing or equipment for the prote inspection procedures, cleaning and sanilogs or records, and such tools and resoumanufacturer's guidelines for assembly of during repair or maintenance	tation supplies, urces as are indi	maintenance cated by the	
Candidate Directive:		"Perform inspection and any necessary no provided equipment, identify issues found record-keeping".			
NO.		TASK STEPS	TEST		
NO.			Successful	Unsuccessful	
1	_	, defects, and wear were identified and or repaired			
2	Equipme	ent functioned as designed			
3	Preventive maintenance was performed consistent with the manufacturer's recommendations.				
4	Preventive maintenance was documented consistent with the manufacturer's recommendations.				
Eval	uator/Car	ndidate Comments:			





Cano	indidate:			Successful
Evaluator:			 Ur	nsuccessful 🗌
Date	:		1006	-PROCESS-08
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.3		
Task		Maintain rescue equipment		
Performance Outcome:		The operational status of equipment is version components are checked for operation, or reported as indicated by standard operations subject to replacement protocol are correspondent.	leficiencies are r ing procedure, a	epaired or and items
by the manufacturer's guidelines, ins		Given maintenance logs and records, too by the manufacturer's guidelines, inspect replacement protocol, and organizational	tion procedures,	equipment
	didate ctive:	"Perform inspection and any necessary necessar		•
		- 1 0 1 C 0 - 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	TE	ST
NO.		TASK STEPS	Successful	Unsuccessful
1	The operand docu	rational status of equipment was verified umented		
2	All comp	onents were checked for operation		
3		cies were repaired or reported as d by standard operating procedure		
4	Items subject to replacement protocol were correctly disposed of and changed			
5	All logs a	and records were completed		
Eval	Evaluator/Candidate Comments:			



ROPE OPERATIONS- NFPA 1006

Cano	Candidate:			Successful	
Evaluator:			U	nsuccessful 🗌	
Date	:			1006-SKILL-09	
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.4			
Task	(:	Demonstrate knots, bends, and hitches			
Performance Outcome:		The knots are dressed, recognizable, and	d backed up as	required	
Cond	ditions:	Given ropes, webbing, and a list of knots	used by the ag	ency	
Candidate Directive:		"Correctly and completely tie each knot, list".	oend or hitch on	the provided	
_					
NO.		TASK STEPS	Successful	ST Unsuccessful	
1	The knot	s were dressed	- Cassessia.	- Chicacoccian	
2	Recogniz	zable			
3	Backed (up as required			
Evaluator/Candidate Comments:					





Candidate:				Successful
Evaluator:		Ur	nsuccessful	
Date:			1006	-PROCESS-10
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.5		
Task	:	Construct a single-point anchor system		
Performance Outcome:		The chosen anchor system fits the incide the expected load, and does not interfere efficient anchor point is chosen, the need assessed and used as required, the anch loaded prior to being placed into service, is maintained throughout the operation.	with rescue ope for redundant a nor system is ins	erations, an nchor points is pected and
Cond	ditions:	Given life safety rope and other auxiliary	rope rescue equ	ipment
Candidate Directive:		"Using the provided equipment, construct system".	t a single-point a	nchor
NO.		TASK STEPS	TE	ST
NO.		IASK STEPS	Successful	Unsuccessful
1	The chos	sen anchor system fit the incident needs	Successful	Unsuccessful
		sen anchor system fit the incident needs sen anchor system met or exceeded the	Successful	Unsuccessful
1	The chose	sen anchor system fit the incident needs sen anchor system met or exceeded the	Successful	Unsuccessful
1 2	The chose expected. The chose rescue of the ch	sen anchor system fit the incident needs sen anchor system met or exceeded the d load sen anchor system did not interfere with	Successful	Unsuccessful
1 2 3	The chose expected. The chose rescue of An efficient The needs	sen anchor system fit the incident needs sen anchor system met or exceeded the d load sen anchor system did not interfere with perations	Successful	Unsuccessful
1 2 3 4	The chose expected. The chose rescue of An efficient assessed. The anche assessed the anche assessed the anche assessed.	sen anchor system fit the incident needs sen anchor system met or exceeded the d load sen anchor system did not interfere with perations ent anchor point was chosen d for redundant anchor points was	Successful	Unsuccessful
1 2 3 4 5	The chose expected The chose rescue of An efficient The need assessed The anche prior to be The integral to the chosen to the ch	sen anchor system fit the incident needs sen anchor system met or exceeded the d load sen anchor system did not interfere with perations ent anchor point was chosen d for redundant anchor points was d and used as required nor system was inspected and loaded	Successful	Unsuccessful
1 2 3 4 5 6	The chose expected The chose rescue of An efficient The need assessed The ancher prior to be throughout throughout the chose of the cho	sen anchor system fit the incident needs sen anchor system met or exceeded the d load sen anchor system did not interfere with perations ent anchor point was chosen d for redundant anchor points was d and used as required nor system was inspected and loaded seing placed into service grity of the system was maintained	Successful	Unsuccessful





Candidate:	Successful
Evaluator:	Unsuccessful
Date:	1006-PROCESS-11
Standard:	NFPA 1006 – 2021 edition – 5.2.6
Task:	Construct a multiple-point anchor system
Performance Outcome:	The chosen anchor system fits the incident needs, the system strength meets or exceeds the expected load and does not interfere with rescue operations, equipment is visually inspected prior to being put in service, the most appropriate anchor points are chosen, the anchor system is system safety checked prior to being placed into service, the integrity of the system is maintained throughout the operation, and the force will be distributed — proportionally or disproportionally — between more than one anchor point.
Conditions:	Given life safety rope and other auxiliary rope rescue equipment
Candidate Directive:	"Using the provided equipment, construct a multiple-point anchor system".

NO.	TASK STEPS	TEST	
NO.	IASK SIEFS	Successful Unsuccessfu	Unsuccessful
1	The chosen anchor system fit the incident needs		
2	The system strength met or exceeded the expected load and did not interfere with rescue operations		
3	Equipment was visually inspected prior to being put in service		
4	The most appropriate anchor points were chosen		
5	The anchor system was system safety checked prior to being placed into service		
6	The integrity of the system was maintained throughout the operation		
7	The force was distributed — proportionally or disproportionally — between more than one anchor point		



ROPE OPERATIONS- NFPA 1006

Evaluator/Candidate Comments:				





Candidate:			Successful	
Evaluator:			Uı	nsuccessful
Date	: <u> </u>		1006	-PROCESS-12
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.7		
Task	:	Conduct a system safety check		
	ormance ome:	A physical/visual check of the system is na load test is performed prior to life-loading confirmation of these actions is announce life-loading the rope rescue system.	ng the system, a	and verbal
Cond	ditions:	Given a rope rescue system and rescue p	personnel	
Candidate Directive:		"Conduct a system safety check of the as	sembled rope r	escue system".
NO		TACK STEDS	TE	ST
NO.		TASK STEPS	TE Successful	ST Unsuccessful
NO.		TASK STEPS al/visual check of the system was made e proper rigging		
	to ensure	al/visual check of the system was made		
1	to ensure A load te system Verbal co announce	al/visual check of the system was made e proper rigging		
1 2 3	to ensure A load te system Verbal co announce the rope	al/visual check of the system was made e proper rigging est was performed prior to life-loading the onfirmation of these actions was ed and acknowledged before life-loading		
1 2 3	to ensure A load te system Verbal co announce the rope	al/visual check of the system was made e proper rigging est was performed prior to life-loading the onfirmation of these actions was ed and acknowledged before life-loading rescue system.		
1 2 3	to ensure A load te system Verbal co announce the rope	al/visual check of the system was made e proper rigging est was performed prior to life-loading the onfirmation of these actions was ed and acknowledged before life-loading rescue system.		





Candidate:				Successful
Evaluator:		U	nsuccessful	
Date:	:		1006	-PROCESS-13
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.8		
Task	:	Place edge protection		
Performance Outcome:		The rope or webbing is protected from abrasion or cutting, the rescuer is safe from falling while placing the edge protection, the edge protection is secure, and the rope or webbing is securely placed on the edge protection.		
Cond	ditions:	Given life safety rope or webbing traversing a sharp or abrasive edge, edge protection, and other auxiliary rope rescue equipment		
	didate ctive:	"Place edge protection in the assembled	rope rescue sys	etem".
NO.		TASK STEPS		ST
	TI		Successful	Unsuccessful
1	-	e or webbing was protected from or cutting		
2		cuer was safe from falling while placing protection		
3		e protection was secure		
4	The rope or webbing was securely placed on the edge protection.			
Evalu	uator/Car	ndidate Comments:		





Cano	Candidate:			Successful
Evalu	Evaluator:		Uı	nsuccessful
Date:		1006	-PROCESS-14	
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.9		
Task	:	Construct a system intended to provide be tensioned rope system	elay within a sir	igle- or two-
Performance Outcome:		The system is capable of arresting a fall, a fall will not result in system failure, the system is not loaded unless actuated, actuation of the system will not injure or otherwise incapacitate the belay operator, the belay operator is not rigged into the equipment components of the system, and the system is suitable to the site and is connected to an anchor system and the load.		
		Given life safety rope, anchor systems, PPE, and rope rescue equipment		
	didate ctive:	"Construct a belay system within the provrope system".	rided single- or t	wo-tensioned
NO		TAOK OTEDO	TE	ST
NO.		TASK STEPS	Successful	Unsuccessful
1		em was capable of arresting a fall		
2	A fall wo	uld not result in system failure		
3	The syst	em was not loaded unless actuated		
4		n of the system would not injure or e incapacitate the belay operator		
5	The belay operator was not rigged into the equipment components of the system			
6	The syst	em was suitable to the site		
7	The syst	em was connected to an anchor system		
8	The syst	em was connected to the load		
Evalı	uator/Can	didate Comments:		





Candidate:				Successful
Evaluator:		U	nsuccessful 🗌	
Date:			1006-SKILL-15	
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.10		
Task	κ:	Operate a system intended to provide be tensioned rope system during a lowering	•	
Performance Outcome:		The potential fall factor is minimized, the normal lowering and raising operations, the for actuation at all times during the opera attentive at all times during the operation continually monitored, and the belay open belay device as designed.	he belay system tion, the belay o , the load's posi rator moves rop	n is prepared operator is tion is e through the
Conditions:		Given an operating lowering or raising mechanical advantage system, a specified minimum travel distance for the load, a system, and a load		
	didate ctive:	"Operate the provided belay system during operation".	ng a raising or lo	owering
			TE	ST
NO.		TASK STEPS	Successful	Unsuccessful
1	The pote	ential fall factor was minimized		
2		y was not actuated during normal and raising operations		
3		y system was prepared for actuation at during the operation		
4	The belay operator was attentive at all times during the operation			
5	The load	's position was continually monitored		
6		y operator moved rope through the belay s designed		
Eval	uator/Car	ndidate Comments:		





Candidate:				Successful
Evaluator:			Ur	nsuccessful
Date: 1006-SKILL-				1006-SKILL-16
Standard: NFPA 1006 – 2021 edition – 5.2.11				
Task	:	Belay a falling load in a high-angle enviro	onment	
Performance Outcome: The belay line is not taut until the load is falling, the belay device is actuated when the load falls, the fall is arrested in a manner that minimizes the force transmitted to the load, the belay operator util the belay device as designed, and the belay operator is not injure otherwise incapacitated during actuation of the belay system			ner that erator utilizes not injured or	
Cond	ditions:	Given a belay and a failed line creating a	dropped load	
Candidate Directive: "Belay the falling load in the falling load		"Belay the falling load in the provided sys	item".	
NO.		TASK STEPS	TE Successful	ST Unsuccessful
1	The bela	y line was not taut until the load was	Odecessiai	Orisuccessiui
2	The bela	y device was actuated when the load fell		
3		was arrested in a manner that minimized transmitted to the load		
4	The bela	y operator utilized the belay device as		
5	The belay operator was not injured or otherwise			
Evalı	uator/Car	ndidate Comments:		





Candidate:			Successful	
Evaluator:		 Uı	nsuccessful 🗌	
Date:		1006	-PROCESS-17	
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.12		
Task	' = \	Construct a fixed rope system		
Outcome: connected to an anchor check is performed and		The system constructed can accommodate connected to an anchor system and the light check is performed and the results meet descending or ascending operations	oad, and a syste	em safety
Cond	ditions:	Given an anchor system, a life safety rop	e, and rope reso	cue equipment
Candidate Directive:		"Using the provided scene and equipment, construct a fixed-rope system".		
NO.		TASK STEPS		ST
	The syst	em constructed accommodated the load	Successful	Unsuccessful
1		om comendated decommedated and read		
2		em was efficient		
•	The syst			
2	The syst	em was efficient		
2	The system results m	em was efficient em was connected to an anchor system		
2 3 4 5	The syst The syst The syst A system results m descend	em was efficient em was connected to an anchor system em was connected to the load n safety check was performed and the net the incident requirements for		
2 3 4 5	The syst The syst The syst A system results m descend	em was efficient em was connected to an anchor system em was connected to the load a safety check was performed and the net the incident requirements for ing or ascending operations		
2 3 4 5	The syst The syst The syst A system results m descend	em was efficient em was connected to an anchor system em was connected to the load a safety check was performed and the net the incident requirements for ing or ascending operations		





NO.	TASK STEPS		С	RITERIA		
NO.	IASK SIEPS	4	3	2	1	Points
1	The system constructed accommodated the load	The system constructed completely accommoda ted the load	The system constructed mostly accommodat ed the load	The system constructe d somewhat accommod ated the load	The system constructe d did not accommod ate the load	
2	Was efficient	Was completely efficient	Was mostly efficient	Was somewhat efficient	Was not efficient	
3	Was connected to an anchor system and the load	Was completely connected to an anchor system and the load	Was mostly connected to an anchor system and the load	Was somewhat connected to an anchor system and the load	Was not connected to an anchor system and the load	
4	A system safety check was performed and the results met the incident requirements for descending or ascending operations	A system safety check was completely performed and the results met the incident requirement s for descending or ascending operations	A system safety check was mostly performed and the results met the incident requirements for descending or ascending operations	A system safety check was somewhat performed and the results met the incident requiremen ts for descendin g or ascending operations	A system safety check was not performed and the results did not meet the incident requiremen ts for descendin g or ascending operations	





Candidate:			Successful	
Evaluator:		U	nsuccessful	
Date:			1006	-PROCESS-18
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.13		
Task	:	Construct a lowering system		
Performance Outcome: The system can accommodate the load, is efficient, is capable of controlling the descent, is capable of holding the load in place of lowering with minimal effort over the required distance, and is connected to an anchor system and the load			olace or	
Conditions:		Given an anchor system, life safety rope(s), descent control device, and auxiliary rope rescue equipment		
Candidate Directive:		"Using the provided scene and equipment system".	it, construct a lo	wering
NO.		TASK STEPS	TE Successful	ST
1	The syst	em accommodated the load	Successiui	Unsuccessful
2	The syst	em was efficient		
3	The syst descent	em was capable of controlling the		
4	The system was capable of holding the load in place or lowering with minimal effort over the required distance			
5	The system was connected to an anchor system and the load			
6	The syst	em was connected to the load		
Eval	uator/Can	ndidate Comments:		





Candidate:			Successful	
Evaluator:		 Ur	nsuccessful	
Date:			1006	-PROCESS-19
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.14		
Task	(Direct a lowering operation in a high-ang	le environment	
Performance Outcome: The movement is controlled, the load can be held in place when needed, operating methods do not stress the system to the point of failure, rope commands are used to direct the operation, and potenti problems are identified, communicated, and managed.			he point of	
Cond	ditions:	Given rescue personnel, an established minimum travel distance for the load, and		
Candidate Directive: "Using the provided lowering system and person operation to move the load the indicated distance		•	ct the lowering	
			TF	ST
NO.		TASK STEPS	Successful	ST Unsuccessful
NO.	The mov	TASK STEPS rement was controlled		_
				_
1	The load	rement was controlled		_
1 2	The load Operatin the point	rement was controlled I could be held in place when needed g methods did not stress the system to of failure mmands were used to direct the		_
1 2 3	The load Operatin the point Rope co- operation Potential	rement was controlled I could be held in place when needed g methods did not stress the system to of failure mmands were used to direct the		_
1 2 3 4 5	The load Operatin the point Rope co operation Potential commun	rement was controlled I could be held in place when needed g methods did not stress the system to of failure mmands were used to direct the n I problems were identified,		_
1 2 3 4 5	The load Operatin the point Rope co operation Potential commun	rement was controlled I could be held in place when needed ag methods did not stress the system to a of failure mmands were used to direct the and I problems were identified, icated, and managed		_
1 2 3 4 5	The load Operatin the point Rope co operation Potential commun	rement was controlled I could be held in place when needed ag methods did not stress the system to a of failure mmands were used to direct the and I problems were identified, icated, and managed		_
1 2 3 4 5	The load Operatin the point Rope co operation Potential commun	rement was controlled I could be held in place when needed ag methods did not stress the system to a of failure mmands were used to direct the and I problems were identified, icated, and managed		_





Candidate:				Successful	
Evaluator:			Unsuccessful		
Date:			1006-SKILL-20		
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.15			
Task	:	Construct a simple rope mechanical adva	ntage system		
	ormance ome:	The system constructed can accommoda connected to an anchor system and the	•	efficient, and is	
Cond	ditions:	Given life safety rope, carabiners, pulleys, rope grab devices, and auxiliary rope rescue equipment			
	didate ctive:	"Using the provided equipment, create a system".	mechanical ad	lvantage	
NO.		TASK STEPS	7	EST	
140.			Successful	Unsuccessful	
1	The syst	em constructed could accommodate the			
2	The syst	em was efficient			
3	The syst	em was connected to an anchor system			
4	The syst	em was connected to the load			
Evaluator/Candidate Comments:					
Evalı	uator/Can	ndidate Comments:			
Evalu	uator/Can	ndidate Comments:			
Evalu	uator/Can	ndidate Comments:			
Evalu	uator/Can	ndidate Comments:			





Candidate:		Successful L		
Evaluator:	Evaluator:		nsuccessful	
Date:		1006	S-PROCESS-21	
Standard:	NFPA 1006 – 2021 edition – 5.2.16			
Stanuaru.	NFFA 1006 – 2021 editio11 – 5.2.16			
Task:	Direct a team in the operation of a simple system in a high-angle raising operation	e rope mechanic	al advantage	
Performance Outcome: The movement is controlled, a reset is accomplished, the load can held in place when needed, operating methods do not stress the system to the point of failure, commands are used to direct the operation, and potential problems are identified, communicated, managed.				
Conditions: Given rescue personnel, an established rope rescue system incorporating a simple rope mechanical advantage system, a speciminimum travel distance for the load, a load to be moved, and an anchor system				
Candidate Directive:	"Using the provided high-angle raising of the use of the mechanical advantage sys	•	sonnel, direct	
NO	TAOK OTEDO	TE	ST	
NO.	TASK STEPS	Successful	Unsuccessful	
1 The mo	vement was controlled			
2 A reset	was accomplished			
3 The load	d could be held in place when needed			
4 '	ng methods did not stress the system to at of failure			
5 Comma	nds were used to direct the operation			
h	al problems were identified, nicated, and managed			
Evaluator/Ca	ndidate Comments:			





Candidate:			Successful		
Evaluator:		Ur	nsuccessful		
Date:			1006	-PROCESS-22	
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.17			
Task: Construct a compound rope mechanical advantage system			m		
Outcome: required to lift the load, operation minimized, the system is efficient		The system constructed accommodates required to lift the load, operational interferminimized, the system is efficient, a system and the system is connected to an anchorage of the system is connecte	erence is factore em safety check	d and is completed,	
Cond	ditions:	l • • • • • • • • • • • • • • • • • • •	Given a load, an anchor system, life safety rope, carabiners, pulleys, rope grab devices, and rope rescue equipment		
Candidate Directive:		"Using the provided equipment, construct a compound rope mechanical advantage system".			
				^=	
NO.		TASK STEPS	TE Successful		
NO.	The syst	TASK STEPS em constructed accommodated the load	Successful	Unsuccessful	
	The syst				
1	The syst required	em constructed accommodated the load em constructed reduced the force to lift the load nal interference was factored and			
1 2	The syst required Operatio minimize	em constructed accommodated the load em constructed reduced the force to lift the load nal interference was factored and			
1 2 3	The syst required Operatio minimize The syst	em constructed accommodated the load em constructed reduced the force to lift the load nal interference was factored and			
1 2 3 4	The syst required Operatio minimize The syst	em constructed accommodated the load em constructed reduced the force to lift the load nal interference was factored and ed em was efficient			
1 2 3 4 5	The syst required Operatio minimize The syst A system The syst	em constructed accommodated the load em constructed reduced the force to lift the load nal interference was factored and ed em was efficient n safety check was completed			
1 2 3 4 5 6 7	The syst required Operation minimized The syst A system The syst The syst	em constructed accommodated the load em constructed reduced the force to lift the load nal interference was factored and ed em was efficient n safety check was completed em was connected to an anchor system			
1 2 3 4 5 6 7	The syst required Operation minimized The syst A system The syst The syst	em constructed accommodated the load em constructed reduced the force to lift the load nal interference was factored and ed em was efficient n safety check was completed em was connected to an anchor system em was connected to the load			





Candidate:			Successful	
Evaluator:		U	nsuccessful	
Date:		1006	6-PROCESS-23	
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.18		
Task: Direct the operation of a compound rope mechanical in a high-angle environment		mechanical adv	vantage system	
Outcome:		A system safety check is performed; a reset is accomplished, and the movement is controlled; the load can be held in place when needed; operating methods do not stress the system to the point of failure; operational commands are clearly communicated; and potential problems are identified, communicated, and managed.		
Conditions: Given a rope rescue system incorporating a compound rope mechanical advantage system and a load to be moved, and a sp minimum travel distance for the load				
Candidate Directive:		"Using the provided environment and per compound rope mechanical advantage s		ne use of the
				
NO.		TASK STEPS	Successful	Unsuccessful
1	A system	safety check was performed		
2	A reset v	vas accomplished		
3	The mov	ement was controlled		
4	The load	could be held in place when needed		
5	•	g methods did not stress the system to of failure		
6	Operatio commun	nal commands were clearly icated		
7		problems were identified, icated, and managed		
Eval	uator/Can	didate Comments:		





Candidate:			Successful	
Evaluator:		U	nsuccessful 🗌	
Date:				1006-SKILL-24
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.19		
		Negotiate an edge while attached to a ro high-angle lowering and raising operation		m during a
Performance Outcome: Risk to the rescuer is minimized; the means of attachment to the rescue system is secure; and all projections and edges are negotiate while minimizing risks to the rescuer or equipment.			-	
Conditions: Given a rope rescue system, a specified the rescuer, life safety harnesses, an edgand raise, and specialized equipment new		ge to negotiate o	during the lower	
Candidate Directive:		"Using the provided rope-rescue system, working in the high-angle raising and low	•	•
NO		TASK STEPS		ST
NO.	Risk to th	TASK STEPS	Successful	Unsuccessful
1		ne rescuer was minimized		
	The mea			
1	The mea	ne rescuer was minimized ans of attachment to the rope rescue vas secure ctions and edges were negotiated while		
1 2	The mea system v All projec minimizir	ne rescuer was minimized ans of attachment to the rope rescue was secure		
1 2 3 4	The mea system v All projec minimizin All record	ne rescuer was minimized ans of attachment to the rope rescue was secure ctions and edges were negotiated while and risks to the rescuer or equipment	Successful	
1 2 3 4	The mea system v All projec minimizin All record	ne rescuer was minimized ans of attachment to the rope rescue was secure ctions and edges were negotiated while and risks to the rescuer or equipment ds and documentation completed	Successful	
1 2 3 4	The mea system v All projec minimizin All record	ne rescuer was minimized ans of attachment to the rope rescue was secure ctions and edges were negotiated while and risks to the rescuer or equipment ds and documentation completed	Successful	
1 2 3 4	The mea system v All projec minimizin All record	ne rescuer was minimized ans of attachment to the rope rescue was secure ctions and edges were negotiated while and risks to the rescuer or equipment ds and documentation completed	Successful	





Candidate:			Successful	
Evaluator:			U	nsuccessful
Date	:		1006	S-PROCESS-25
Stan	dard:	NFPA 1006 – 2021 edition – 5.2.20		
Task: Prepare for transfer of victims				
Performance Outcome: Rescuers and victims are protected from hazards, victim injuries illnesses are managed, and victims are delivered to the EMS prowith information regarding the history of the rescue activity and victims.			EMS provider	
Cond	ditions:	Given diagnostic and packaging equipme EMS agency	ent and an actua	al or simulated
Candidate Directive:		"Using the scene, simulated victim and p transfer the victim to EMS".	ersonnel provide	ed, prepare to
NO.		TASK STEPS		ST
1	Rescuer	s and victims were protected from	Successful	Unsuccessful
2		juries or illnesses were managed		
3	Victims were delivered to the EMS provider with information regarding the history of the rescue activity and victim conditions.			
Evaluator/Candidate Comments:				
	uator/Car	ididate Comments:		
	uator/Car	ididate Comments:		
	uator/Car	ididate Comments:		
	uator/Car	ididate Comments:		





Candidate:		Successful
Evaluator:		Unsuccessful
Date:		1006-PROCESS-26
Standard:	NFPA 1006 – 2021 edition – 5.2.21	
Task:	Direct a litter-lowering and litter-raising operation environment	ion in a low-angle
Performance Outcome:		
Conditions:	Given rescue personnel, litter tender(s), an est lowering/mechanical advantage system, a spe distance for the load and a victim packaged in	cified minimum travel
Candidate Directive:	"Using the provided rescue system and low-ar the lowering and raising of the litter for the spe	

NO.	TASK STEPS	TEST	
NO.		Successful	Unsuccessful
1	The litter was attached to the lowering/raising and belay systems		
2	Movement was controlled		
3	Litter tender(s) were used to manage the litter during the lower and raise		
4	The litter could be held in place when needed		
5	Operating methods did not stress the system to the point of failure		
6	Rope commands were used to direct the operation		
7	Potential problems were identified, communicated, and managed		



ROPE OPERATIONS- NFPA 1006

Evaluator/Candidate Comments:			





Candidate:			Successful		
Evalu	uator:		U	nsuccessful	
Date:			1006	S-PROCESS-27	
Standard:		NFPA 1006 – 2021 edition – 5.2.22			
Task:		Operate as a litter tender in a low-angle lowering or raising operation			
Performance Outcome:		Risks to victims and rescuers are minimized; the means of attachment to the rope rescue system is secure; and the terrain is negotiated while minimizing risks to equipment or persons.			
Conditions:		Given a rope rescue system, a specified minimum travel distance for the litter tender, life safety harnesses, litters, bridles, and specialized equipment necessary for the environment			
Candidate Directive:		"Using the provided rescue system and low-angle lowering or raising operation, operate as litter tender for the specified distance".			
NO.		TASK STEPS		ST Unsuccessful	
NO. 1	Risks to	TASK STEPS victims and rescuers were minimized	TE Successful	EST Unsuccessful	
	The mea				
1	The mea system v	victims and rescuers were minimized ins of attachment to the rope rescue			
1 2 3	The mea system v The terra to equipr	victims and rescuers were minimized ans of attachment to the rope rescue was secure ain was negotiated while minimizing risks			
1 2 3	The mea system v The terra to equipr	victims and rescuers were minimized ins of attachment to the rope rescue was secure ain was negotiated while minimizing risks ment or persons			
1 2 3	The mea system v The terra to equipr	victims and rescuers were minimized ins of attachment to the rope rescue was secure ain was negotiated while minimizing risks ment or persons			
1 2 3	The mea system v The terra to equipr	victims and rescuers were minimized ins of attachment to the rope rescue was secure ain was negotiated while minimizing risks ment or persons			
1 2 3	The mea system v The terra to equipr	victims and rescuers were minimized ins of attachment to the rope rescue was secure ain was negotiated while minimizing risks ment or persons			





Candidate:		Successful
Evaluator:		Unsuccessful
Date:		1006-PROCESS-28
Standard:	NFPA 1006 – 2021 edition – 5.2.23	
Task:	Direct a litter-lowering or litter-raising operation environment	n in a high-angle
Performance Outcome:	The litter is attached to the lowering/raising and is negotiated during a lower and raise; tag lines litter during the lower and raise; the litter can be needed; operating methods do not stress the stailure; rope commands are used to direct the oproblems are identified, communicated, and many little and lit	s are used to manage the e held in place when system to the point of operation; and potential
Conditions:	Given rescue personnel, an established lowering advantage system, a specified minimum travel victim packaged in a litter to be moved, and a redges and projections along the travel path	distance for the load, a
Candidate Directive:	"Using the provided rescue system and high-ar the lowering and raising of the litter for the spe	•

NO.	TACK STEDS TEST		ST
NO.	TASK STEPS	Successful	Unsuccessful
4	The litter was attached to the lowering/raising		
'	and belay systems		
2	An edge was negotiated during lowering and		
	raising		
3	Tag lines were used to manage the litter during		
3	the lowering/raising		
4	The litter could be held in place when needed		
_	Operating methods did not stress the system to		
5	the point of failure		
6	Rope commands were used to direct the		
О	operation		
7	Potential problems were identified,		
/	communicated, and managed		



ROPE OPERATIONS- NFPA 1006

Evaluator/Candidate Comments:			





Candidate:				Successful
Evaluator:			 Ur	nsuccessful
Date:			1006	-PROCESS-29
Standard:		NFPA 1006 – 2021 edition – 5.2.24		
Task:		Terminate a technical rescue operation		
Performance Outcome:		Rescuer risk and site safety are managed, scene security is maintained and custody transferred to a responsible party, personnel and resources are returned to a state of readiness, record keeping and documentation occur, and post event analysis is conducted.		
Cond	ditions:	Given an incident scenario, assigned resources, and site safety data		
Candidate Directive:		"Terminate the provided technical rescue operation".		
NO TACK STEPS			TEST	
NO		TASK STEPS		
NO.		TASK STEPS	TE Successful	ST Unsuccessful
NO.		risk and site safety were managed		
_	Scene se			
1	Scene se	risk and site safety were managed ecurity was maintained and custody ed to a responsible party el and resources were returned to a state		
1 2	Scene se transferre Personne of readin	risk and site safety were managed ecurity was maintained and custody ed to a responsible party el and resources were returned to a state		
1 2 3	Scene se transferre Personne of readin Record k	risk and site safety were managed ecurity was maintained and custody ed to a responsible party el and resources were returned to a state ess		
1 2 3 4	Scene se transferre Personne of readin Record k	risk and site safety were managed ecurity was maintained and custody ed to a responsible party el and resources were returned to a state ess seeping and documentation occurred		
1 2 3 4 5 6	Scene se transferre Personne of readin Record ke Post eve All record	risk and site safety were managed ecurity was maintained and custody ed to a responsible party el and resources were returned to a state ess deeping and documentation occurred int analysis was conducted	Successful	
1 2 3 4 5 6	Scene se transferre Personne of readin Record ke Post eve All record	risk and site safety were managed ecurity was maintained and custody ed to a responsible party el and resources were returned to a state ess deeping and documentation occurred int analysis was conducted ds and documentation completed	Successful	
1 2 3 4 5 6	Scene se transferre Personne of readin Record ke Post eve All record	risk and site safety were managed ecurity was maintained and custody ed to a responsible party el and resources were returned to a state ess deeping and documentation occurred int analysis was conducted ds and documentation completed	Successful	